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Beginner's Guide on PyTorch from Linear Regression

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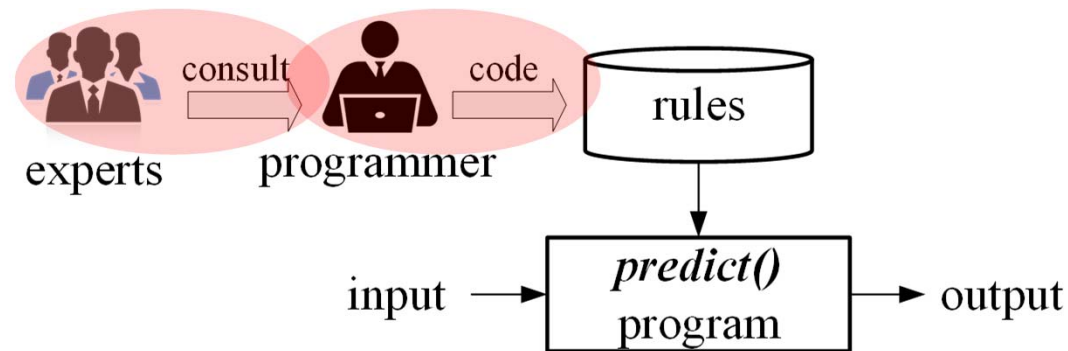


Outline

- Introduction
 - About Machine Learning
 - Basic Learning Paradigm
 - Support from PyTorch
- Linear Regression
 - Problem Description
 - Gradient Descent Algorithm
 - Numpy Program
- PyTorch Programming
 - Autograd and Optimizer
 - Data Providing
 - Model Building

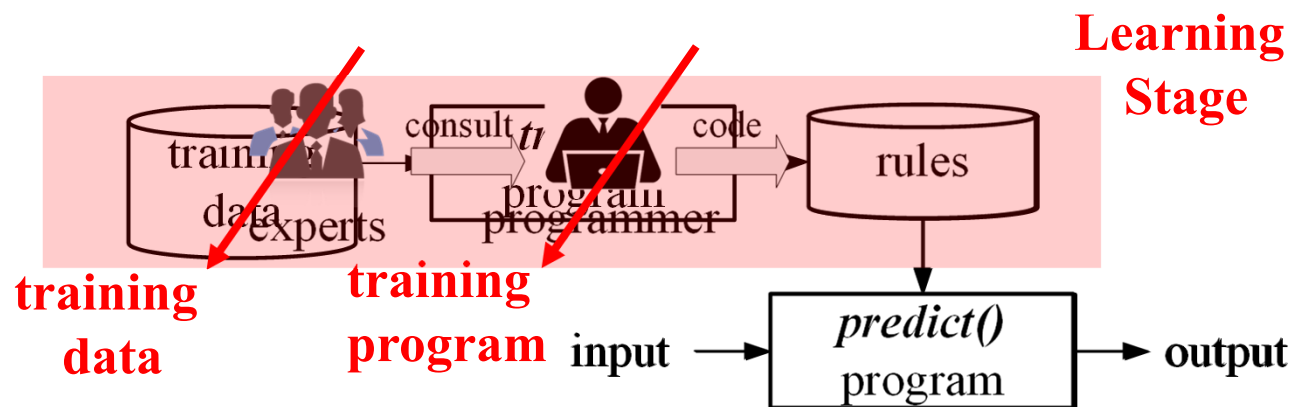
Introduction

- About Machine Learning (ML)
 - Traditional programming is to code the **rules** by the programmer
 - the rules is for producing output
 - the rules are obtained by consulting domain experts



Introduction

- About Machine Learning (ML)
 - ML is to learn the rules (relations between input and output) from **training data**
 - programmer $\rightarrow$ training program
 - experts $\rightarrow$ data





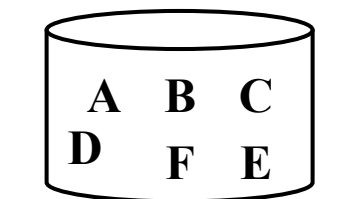
Introduction

- Basic Learning Paradigm
 - Step 1: randomly initialize model to be trained
 - Step 2: repeatedly visit all items in the training dataset (with M data items) for N times (epochs)
 - Step 2.1: randomly shuffle the data items
 - Step 2.2: sequentially load m data items (mini-batch) to update the model (totally, M/m updates)

Introduction

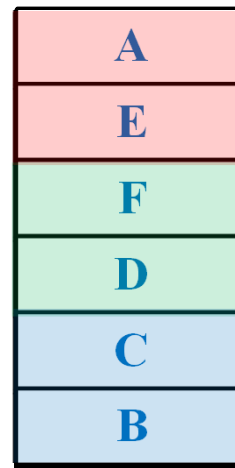
- Example: ($M = 6, m = 2, N = 3$)

3rd Epoch



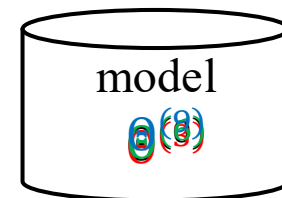
six items in
training dataset
 $M = 6$

randomly
shuffling



memory
queue

sequentially loading
two items ($m = 2$)
to update the model



$$\Theta^{(0)} \xrightarrow{A, E} \Theta^{(1)}$$

$$\Theta^{(1)} \xrightarrow{F, D} \Theta^{(2)}$$

$$\Theta^{(2)} \xrightarrow{C, B} \Theta^{(3)}$$

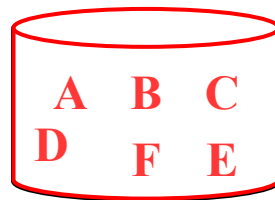


Introduction

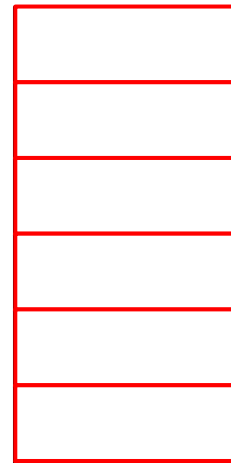
- Support from PyTorch
 - PyTorch was developed by Facebook and is an **machine learning** package for Python language
 - support dataset management and exploring
 - support model building
 - support optimization utilities
 - support parallel processing by using GPU

Introduction

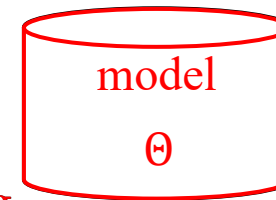
data loading and exploring
memory queue



randomly
shuffling



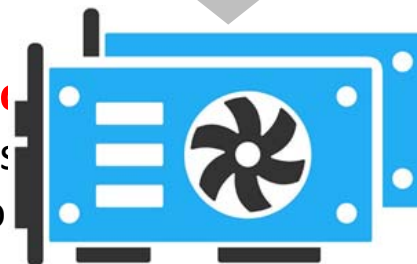
sequentially loading
mini-batch to
update the model



torch.nn subpackage
contain modules and extensible
classes for building ML model

torch.utils data subpackage
contain dataset and loaders to
make data processing easier
data type, similar to Numpy ndarray
but use GPU

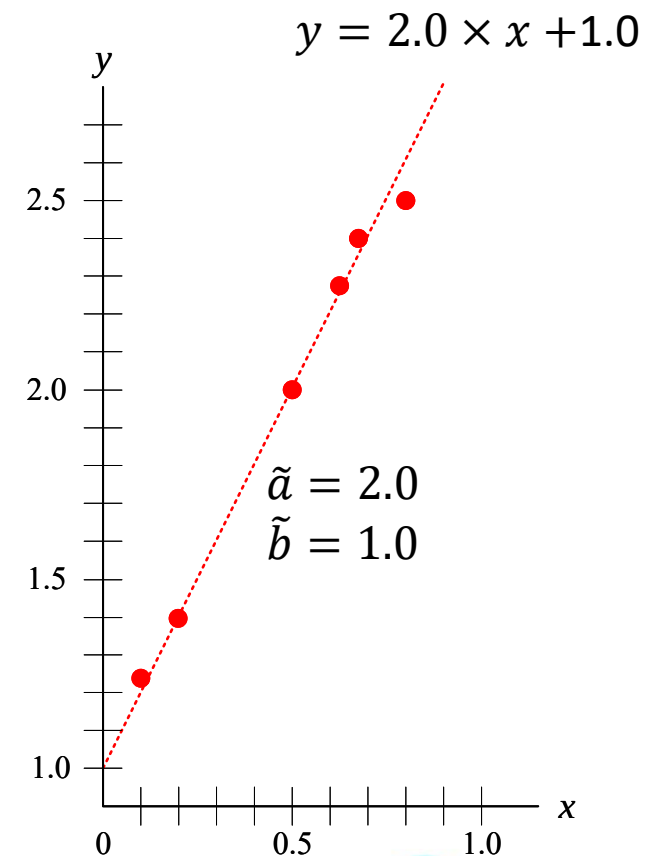
torch.autograd s package
provide
torch.
contain s
operatio



Linear Regression

- Problem Description
 - **Given:** N points $\{(x_i, y_i)\}_{i=1}^N$
sampling from a linear model
 $y_i = ax_i + b$ with noise
 - **Objective:** find the model
parameters $(\tilde{a}, \tilde{b})$ that most fits
these points (minimize **fitting error**)

i	1	2	3	4	5	6
x_i	0.11	0.20	0.49	0.65	0.67	0.83
y_i	1.24	1.40	2.00	2.27	2.41	2.52



Linear Regression

- Problem Description
 - Mean Square Error (MSE) (or called loss) is a way for measuring fitting error

$$L_{MSE}(a, b) = \frac{1}{N} \times \sum_i (y_i - \hat{y}_i)^2$$

ground truth
predicted value
 $\hat{y}_i = a \times x_i + b$

x_i	0.11	0.20	0.49	0.65	0.67	0.83
y_i	1.24	1.40	2.00	2.27	2.41	2.52

$$(a, b) = (1.0, 1.0) \quad \hat{y}_i = 1.0 \times x_i + 1.0$$

$\hat{y}_i$	1.11	1.20	1.49	1.65	1.67	1.83
-------------	------	------	------	------	------	------

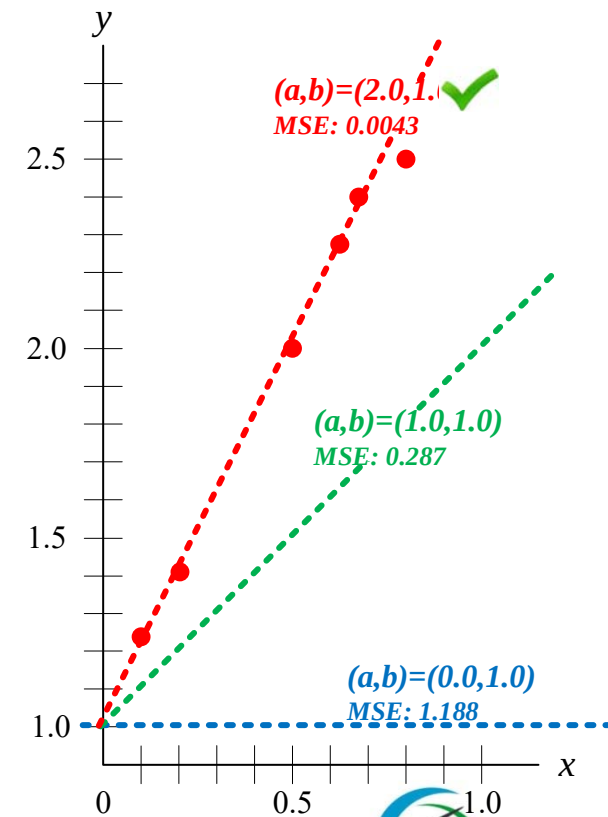
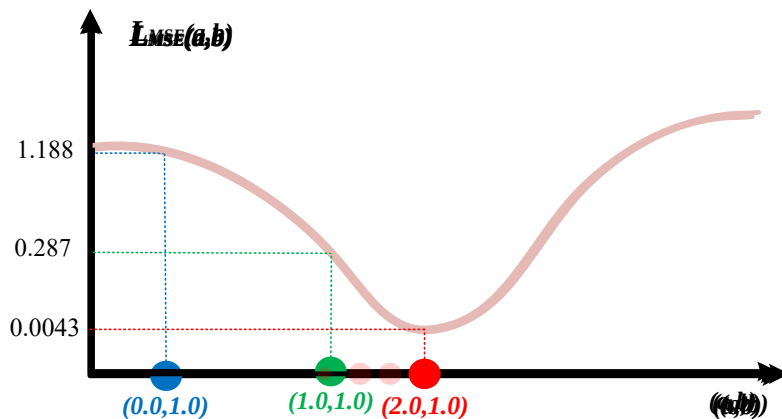
$y_i - \hat{y}_i$	0.13	0.20	0.51	0.62	0.74	0.69
-------------------	------	------	------	------	------	------

$$\begin{aligned}
 L_{MSE}(a = 1.0, b = 1.0) \\
 &= \frac{1}{6} (0.13^2 + 0.20^2 + 0.51^2 \\
 &\quad + 0.62^2 + 0.74^2 + 0.69^2)
 \end{aligned}$$

Linear Regression

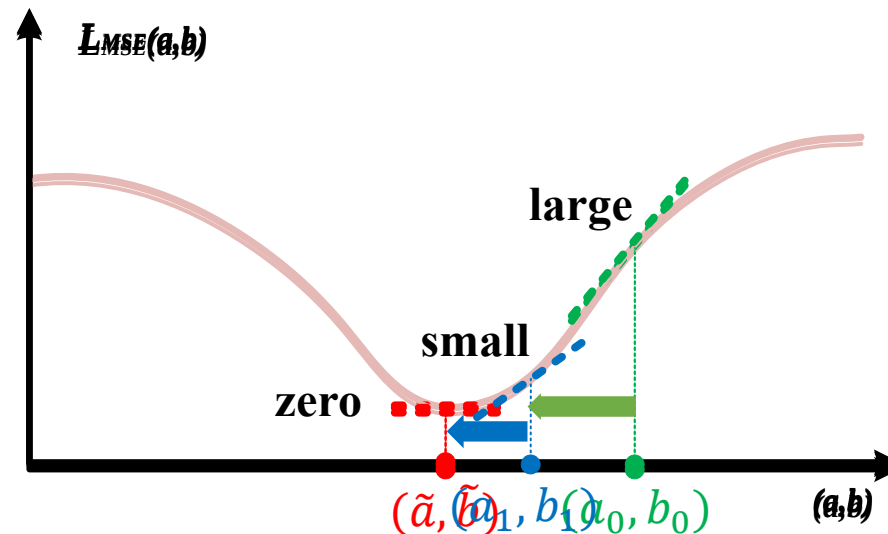
- Problem Description
 - $(\tilde{a}, \tilde{b})$ is the model parameters that minimizes $L_{MSE}(a, b)$

$$(\tilde{a}, \tilde{b}) = \arg \min_{(a,b)} L_{MSE}(a, b)$$



Linear Regression

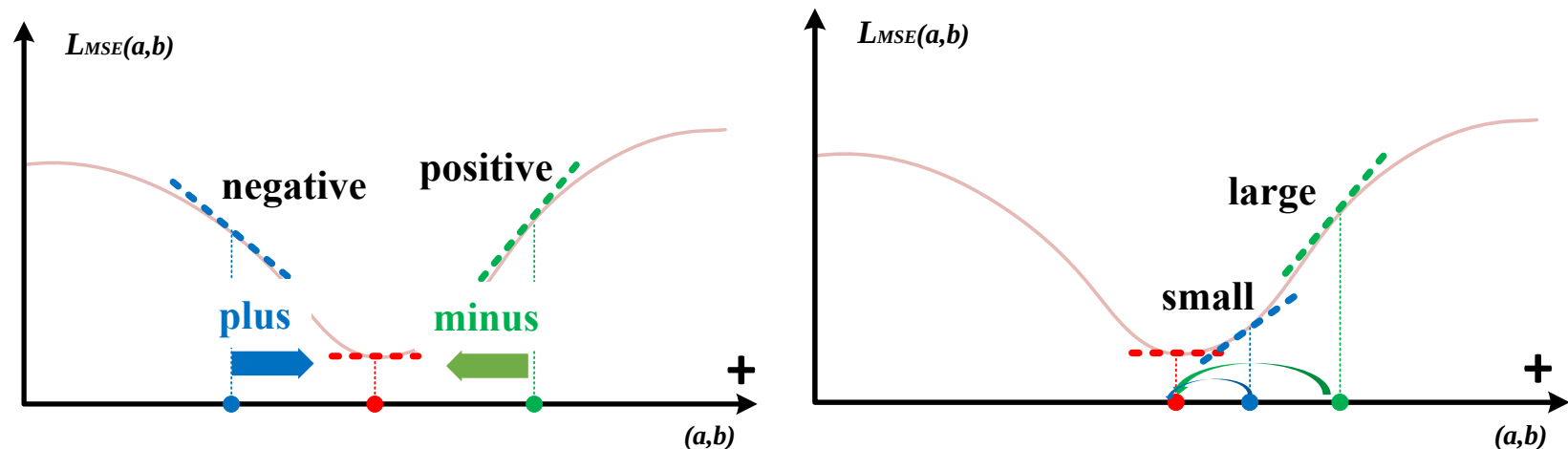
- Gradient Descent Algorithm
 - minimize MSE loss in an **iterative** manner
 - start from a randomly selected point (a_0, b_0)
 - move toward the minimal point with zero gradient by gradually decreasing the gradient





Linear Regression

- Gradient Descent Algorithm
 - take a step **proportional** to the **negative** direction of gradient
 - negative $\rightarrow$ increase (+); positive $\rightarrow$ decrease(-);
 - large $\rightarrow$ far $\rightarrow$ big step; small $\rightarrow$ near $\rightarrow$ small step



Linear Regression

- Gradient Descent Algorithm
 - take a step proportional to the **negative** direction of **gradient**

$$a_{t+1} = a_t + \eta \frac{\partial L_{MSE}(a_t, b_t)}{\partial a}$$

$$b_{t+1} = b_t + \eta \frac{\partial L_{MSE}(a_t, b_t)}{\partial b}$$

- η : learning rate

$$\frac{\partial L_{MSE}(a,b)}{\partial a} = \frac{1}{\partial a} \left(\frac{1}{N} \times \sum_i (y_i - (ax_i + b))^2 \right)$$

$$= \frac{1}{N} \times \sum_i \frac{1}{\partial a} (y_i - (ax_i + b))^2$$

$$= \frac{1}{N} \times \sum_i 2 \times (y_i - (ax_i + b)) \times \frac{1}{\partial a} (y_i - (ax_i + b))$$

$$= \frac{1}{N} \times \sum_i 2 \times (y_i - (ax_i + b)) \times (-x_i)$$

$$\frac{\partial L_{MSE}(a,b)}{\partial b} = \frac{1}{\partial b} \left(\frac{1}{N} \times \sum_i (y_i - (ax_i + b))^2 \right)$$

$$= \frac{1}{N} \times \sum_i \frac{1}{\partial b} (y_i - (ax_i + b))^2$$

$$= \frac{1}{N} \times \sum_i 2 \times (y_i - (ax_i + b)) \times \frac{1}{\partial b} (y_i - (ax_i + b))$$

$$= \frac{1}{N} \times \sum_i 2 \times (y_i - (ax_i + b)) \times (-1)$$

Linear Regression

- Gradient Descent Algorithm

$$a_{t+1} = a_t - \eta \times \frac{\partial L_{MSE}(a_t, b_t)}{\partial a}$$

$$= a_t - \eta \times \left(-2 \times \frac{1}{N} \times \sum_i (y_i - (a_t x_i + b_t)) \times x_i \right)$$

$$b_{t+1} = b_t - \eta \times \frac{\partial L_{MSE}(a_t, b_t)}{\partial b}$$

predicted value at time t
 $\hat{y}_{i,t} = a_t \times x_i + b_t$

$$= b_t - \eta \times \left(-2 \times \frac{1}{N} \times \sum_i (y_i - (a_t x_i + b_t)) \right)$$

Linear Regression

- Step 1: randomly initialize model, (a_0, b_0) be trained
- Step 2: repeatedly visit the dataset for N epochs
 - Step 2.1: randomly shuffle the data items
 - Step 2.2: for each mini-batch to update (a, b)

updating
steps

- Step 2.2.1: compute the $L_{MSE}(a_t, b_t)$
- Step 2.2.2: compute $\frac{\partial L_{MSE}(a_t, b_t)}{\partial a}$ and $\frac{\partial L_{MSE}(a_t, b_t)}{\partial b}$
- Step 2.2.3: update (a, b)

$$a_{t+1} = a_t - \eta \times \frac{\partial L_{MSE}(a_t, b_t)}{\partial a} \quad b_{t+1} = b_t - \eta \times \frac{\partial L_{MSE}(a_t, b_t)}{\partial b}$$

Linear Regression

- NumPy Program
 - use NumPy (Numerical Python) package to implement gradient descent algorithm

```
import numpy      import NumPy package
```

```
data_points = numpy.array([[0.11, 1.24],  
                           [0.20, 1.40],  
                           [0.49, 2.00],  
                           [0.65, 2.27],  
                           [0.67, 2.41],  
                           [0.83, 2.52]])
```

initialize data_points as
a 6x2 numpy array with values

x_i	0.11	0.20	0.49	0.65	0.67	0.83
y_i	1.24	1.40	2.00	2.27	2.41	2.52

initialize hyper-parameters

```
n_epoch = 4000  
batch_size = 2  
eta = 0.01
```

- n_epoch: number of epochs
- batch_size: number of items in a mini-batch
- eta: learning rate

```
a = numpy.random.randn(1)
b = numpy.random.randn(1)
```

Step 1: randomly initialize (a, b)
using **randn()** in numpy.random package

```
for epoch in range(n_epoch):
```

Step 2: repeatedly visit all items
in data_points for n_epoch times

```
numpy.random.shuffle(data_points)
```

Step 2.1: shuffle items in data_points

```
for start_index in range(0, len(data_points), batch_size):
    points = data_points[start_index:start_index+batch_size]
    x = points[:,0]
    y = points[:,1]
```

Step 2.2: sequentially take a mini-batch
for updating a and b

When there are many parameters to be estimated, it is hard
to compute their gradients and update them, respectively

```
a_grad = -2 * ((x * y_error).mean())
b_grad = -2 * (y_error.mean())
```

Step 2.2.2: compute $\frac{\partial L_{MSE}(a_t, b_t)}{\partial a}$
and $\frac{\partial L_{MSE}(a_t, b_t)}{\partial b}$

```
a = a - eta * a_grad
b = b - eta * b_grad
```

Step 2.2.3: update (a, b)
$$a_{t+1} = a_t - \eta \times \frac{\partial L_{MSE}(a_t, b_t)}{\partial a}$$
$$b_{t+1} = b_t - \eta \times \frac{\partial L_{MSE}(a_t, b_t)}{\partial b}$$



PyTorch Programming

- Autograd and Optimizer
 - **autograd** package: include differential operations on **PyTorch tensors**
 - define the model parameters (***a*** and ***b***, in this case) as PyTorch tensors
 - convert the data for updating model parameters to PyTorch tensors
 - perform backward propagation by calling ***backward()*** of loss tensor variable (***mse_loss***, in this case)

```

a = numpy.random.randn(1)
b = numpy.random.randn(1)

```

→

```

a = torch.randn(1, requires_grad=True)
b = torch.randn(1, requires_grad=True)

```

```

for epoch in range(n_epoch):

```

define model parameters (a, b)
as PyTorch tensors

```

    numpy.random.shuffle(data_points)

```

```

    for start_index in range(0, len(data_points), batch_size):
        points = data_points[start_index:start_index+batch_size]
        x = points[:,0]
        y = points[:,1]

```

→

```

        x = torch.FloatTensor(points[:,0])
        y = torch.FloatTensor(points[:,1])

```

convert the data for updating (a, b)
to PyTorch tensors

```

        y_hat = a * x + b
        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()

```

```

        a_grad = -2 * ((x * y_error).mean())
        b_grad = -2 * (y_error.mean())

```

→

```

        mse_loss.backward()

```

```

        a = a - eta * a_grad
        b = b - eta * b_grad

```

compute partial derivatives w.r.t. (a, b)
via back propagation

```

a = torch.randn(1, requires_grad=True)
b = torch.randn(1, requires_grad=True)

for epoch in range(n_epoch):

    numpy.random.shuffle(data_points)

    for start_index in range(0, len(data_points), batch_size):
        points = data_points[start_index:start_index+batch_size]
        x = torch.FloatTensor(points[:,0])
        y = torch.FloatTensor(points[:,1])

        y_hat = a * x + b
        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()

        mse_loss.backward()

        a = a - eta * a_grad
        b = b - eta * b_grad

```



PyTorch Programming

- Autograd and Optimizer
 - ***torch.optim*** package: implement various optimization algorithms, SGD, Adam, etc.
 - create an optimizer object by taking **model parameters** and **learning rate** as arguments
 - update the model parameters by invoking **step()** method of the optimizer
 - zero the gradients of all variables after updating by invoking **zero_grad()** method of the optimizer


```

a = torch.randn(1, requires_grad=True)
b = torch.randn(1, requires_grad=True)

```

create an optimizer object by taking model parameters ($[a, b]$) and learning rate (η) as arguments

```

optimizer = \
torch.optim.SGD([a,b], eta)

```

```

for epoch in range(n_epoch):

```

```

    numpy.random.shuffle(data_points)

```

```

    for start_index in range(0, len(data_points), batch_size):
        points = data_points[start_index:start_index+batch_size]
        x = torch.FloatTensor(points[:,0])
        y = torch.FloatTensor(points[:,1])

```

```

        y_hat = a * x + b
        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()

```

```

        mse_loss.backward()

```

update (a, b) by invoking *step()* of the optimizer

```

        a = a - eta * a_grad
        b = b - eta * b_grad

```

→ `optimizer.step()` zero all gradients by invoking *zero_grad()*

← `optimizer.zero_grad()`


```
a = torch.randn(1, requires_grad=True)
b = torch.randn(1, requires_grad=True)

optimizer = \
    torch.optim.SGD([a,b], eta)

for epoch in range(n_epoch):

    numpy.random.shuffle(data_points)

    for start_index in range(0, len(data_points), batch_size):
        points = data_points[start_index:start_index+batch_size]
        x = torch.FloatTensor(points[:,0])
        y = torch.FloatTensor(points[:,1])

        y_hat = a * x + b
        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()

        mse_loss.backward()

        optimizer.step()
        optimizer.zero_grad()
```

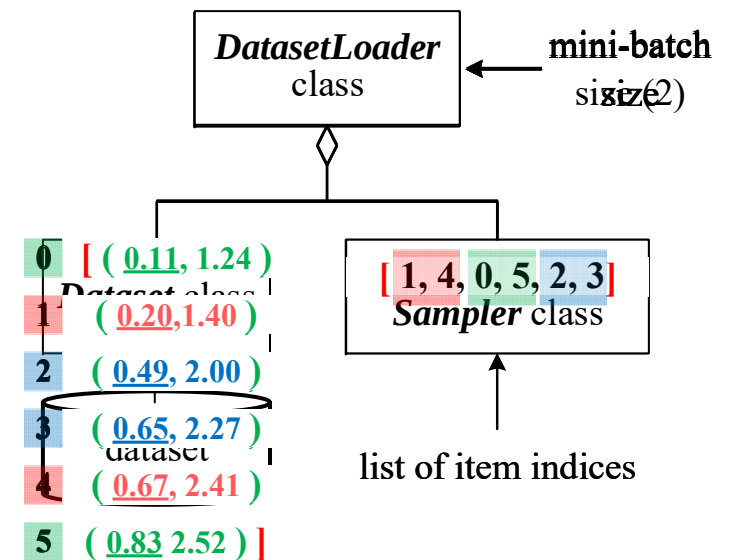
PyTorch Programming

- Data Providing

- Providing data in PyTorch are based on three classes in *torch.utils.data* package

- **Dataset class**: have the interface to index data item(feature + label)
- **SubsetRandomSampler class**: shuffle item indices to provide random sampling
- **DataLoader class**: is an iterator that slices the dataset according to desired min-batch size

mini-batch 0	mini-batch 1	mini-batch 2
$((\underline{0.20}, \underline{0.67}), (\underline{1.40}, \underline{2.41}))$	$((\underline{0.11}, \underline{0.83}), (\underline{1.24}, \underline{2.52}))$	$((\underline{0.49}, \underline{0.65}), (\underline{2.00}, \underline{2.27}))$





PyTorch Programming

- Data Providing
 - declare an class inheriting from **abstract Dataset** class to represent a dataset
 - implement three **abstract** methods
 - **`__init__(self)`**: take arguments needed to build a list of tuples depending on the task at hand
 - **`__getitem__(self, index)`**: return a tuple (feature, label) for the requested data at **indexth** position
 - **`__len__(self)`**: return the number of items (size) in the whole dataset.



PyTorch Programming

- Data Providing
 - create an object of ***Dataset*** class
 - create an object of ***SubsetRandomSampler*** class by taking the **list of item indices** as argument
 - create an object of ***DataLoader*** class by taking three arguments
 - ***Dataset*** object
 - ***SubsetRandomSampler*** object
 - mini-batch size

`class LRDataset(Dataset):` inherit from **Dataset** class

```
def __init__(self, data_points):  
    self.data_points = data_points
```

take the points for linear regression as input and store them to instance variable

self.data_points

```
def __getitem__(self, index):  
    x = torch.tensor(self.data_points[index][0], dtype=torch.float)  
    y = torch.tensor(self.data_points[index][1], dtype=torch.float)
```

define three methods

```
    return x, y
```

return a tuple (x, y) at **index** position as PyTorch tensors

```
def __len__(self):  
    return len(self.data_points)
```

return the number of data points (in this case is 6)

```
lr_dataset = LRDataset(data_points)
```

 create a **dataset** object as **lr_dataset**

```
indices = list(range(len(lr_dataset)))  
sampler = SubsetRandomSampler(indices)
```

 generate a list of item indices and use it to create **SubsetRandomSampler** object as **sampler**

```
lr_loader = DataLoader(dataset=lr_dataset, \  
                        sampler=sampler, \  
                        batch_size = batch_size)
```

take **lr_dataset**, **sampler**, and **batch_size** as arguments to generate **DataLoader** object as **lr_loader**

```
a = torch.randn(1, requires_grad=True)
b = torch.randn(1, requires_grad=True)
```

```
optimizer = \
    torch.optim.SGD([a,b], eta)
```

```
for epoch in range(n_epoch):
```

```
    numpy.random.shuffle(data_points)
```

```
    for start_index in range(0, len(data_points), batch_size):
        points = data_points[start_index:start_index+batch_size]
        x = torch.FloatTensor(points[:,0])
        y = torch.FloatTensor(points[:,1])
```

```
        y_hat = a * x + b
```

```
        y_error = y - y_hat
```

```
        mse_loss = (y_error ** 2).mean()
```

```
        mse_loss.backward()
```

```
        optimizer.step()
```

```
        optimizer.zero_grad()
```



```
for x, y in lr_loader:
```

iterate all mini-batches
provided by *lr_loader*

```
a = torch.randn(1, requires_grad=True)
b = torch.randn(1, requires_grad=True)

optimizer = \
    torch.optim.SGD([a,b], eta)

for epoch in range(n_epoch):
    for x, y in lr_loader:
        y_hat = a * x + b

        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()

        mse_loss.backward()

        optimizer.step()
        optimizer.zero_grad()
```



PyTorch Programming

- Model Building
 - inherit from **abstract *Module*** class to represent a model
 - implement two **abstract** methods
 - ***__init__(self)***: define the model part (parameters a and b in this case)
 - ***forward(self, x)***: give the input x to output prediction

You should **NOT** call `forward()`.

You should call the **whole model** itself to perform forward pass

inherit from **Module** class

```
class LRModel(torch.nn.Module):
```

```
    def __init__(self):
```

```
        super(LRModel, self).__init__()
```

init base class by passing class
name **LRModel** as argument

implements
two methods

```
        self.a = torch.nn.Parameter(torch.rand(1), \
                                     requires_grad=True)
```

```
        self.b = torch.nn.Parameter(torch.rand(1), \
                                     requires_grad=True)
```

```
    def forward(self, x):
```

```
        return self.a * x + self.b
```

randomly set variables a, b as
model parameters to be estimated
and turn on **required_grad** flag

return the current prediction

$$y = a \times x + b$$

```
lr_model = LRModel() create a model as lr_model
```



```
a = torch.randn(1, requires_grad=True)
b = torch.randn(1, requires_grad=True)
```

```
optimizer = \
    torch.optim.SGD([a,b], eta) → lr_model.parameters()
```

```
for epoch in range(n_epoch):
```

replace , [a, b] to with the
parameters in model to **SGD** for
further optimization

```
    for x, y in lr_loader:
```

```
        y_hat = a * x + b → lr_model.train()
                           y_hat = lr_model(x)
```

```
        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()
```

set model as train mode
and predict **y_hat** by invoking
forward() method

```
mse_loss.backward()
```

```
optimizer.step()
optimizer.zero_grad()
```

```
optimizer = \
    torch.optim.SGD(lr_model.parameters(), eta)

for epoch in range(n_epoch):

    for x, y in lr_loader:

        lr_model.train()
        y_hat = lr_model(x)

        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()

        mse_loss.backward()

        optimizer.step()
        optimizer.zero_grad()
```

```
import numpy
import torch
```

import packages

```
from torch.utils.data import Dataset
from torch.utils.data import DataLoader
from torch.utils.data import SubsetRandomSampler
```

```
class LRDataset(Dataset):
```

declare LRDataset class

```
    def __init__(self, data_points):
        self.data_points = data_points

    def __getitem__(self, index):
        x = torch.tensor(self.data_points[index][0], \
                        dtype=torch.float)
        y = torch.tensor(self.data_points[index][1], \
                        dtype=torch.float)

        return x, y

    def __len__(self):
        return len(self.data_points)
```

```
class LRModel(torch.nn.Module):
```

declare LRModel class

```
    def __init__(self):
        super(LRModel, self).__init__()

        self.a = torch.nn.Parameter(torch.rand(1), \
                                     requires_grad=True)
        self.b = torch.nn.Parameter(torch.rand(1), \
                                     requires_grad=True)

    def forward(self, x):
        return self.a * x + self.b
```

```
n_epoch = 4000
batch_size = 2
eta = 0.01
```

set hyper-parameters

define objects for data providing

```
data_points = numpy.array([[0.11, 1.24],
                           [0.20, 1.40], [0.49, 2.00],
                           [0.65, 2.27], [0.67, 2.41],
                           [0.83, 2.52]])
```

```
lr_dataset = LRDataset(data_points)

index = list(range(len(lr_dataset)))
sampler = SubsetRandomSampler(index)
lr_loader = DataLoader(dataset=lr_dataset, \
                      batch_size=batch_size, \
                      sampler=sampler)
```

```
lr_model = LRModel()
```

define model and optimizer

```
optimizer = \
    torch.optim.SGD(lr_model.parameters(), eta)
```

```
for epoch in range(n_epoch):
```

run learning paradigm

```
    for x, y in lr_loader:
```

```
        lr_model.train()
        y_hat = lr_model(x)

        y_error = y - y_hat
        mse_loss = (y_error ** 2).mean()

        mse_loss.backward()

        optimizer.step()
        optimizer.zero_grad()
```

```
print(f'\n{epoch}:{lr_model.a}:{lr_model.b}')
```

